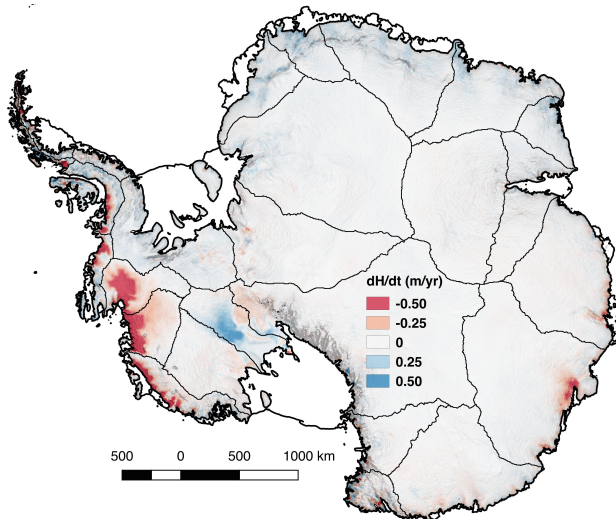




Integration of nearly 30 years of disparate satellite altimetry observations of the Antarctic ice sheet, 1985-2018

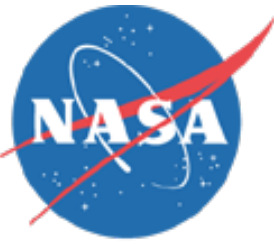


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AGU Meeting 2018, Washington D.C, U.S.A

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²DTU Space, National Space Institute, Technical University of Denmark



Introduction

- Satellite and airborne altimetry provide the longest continuous record from which the mass balance of the Antarctic ice sheet can be derived, starting with the launch of ERS-1 in 1991.
- Accurate knowledge of the long-term mass balance is vital for understanding the geophysical processes governing the ice sheet contribution to present day sea-level rise.
- However, this record is comprised of several different measurement systems: with different orbit parameters, effective topography (sampling, penetration, etc..), measurement configuration (pulse-limited, interferometric, laser etc.).
- This poses a major challenge on the interpretation and reconstruction of consistent elevation-change time series for determining long-term ice sheet trends and variability.

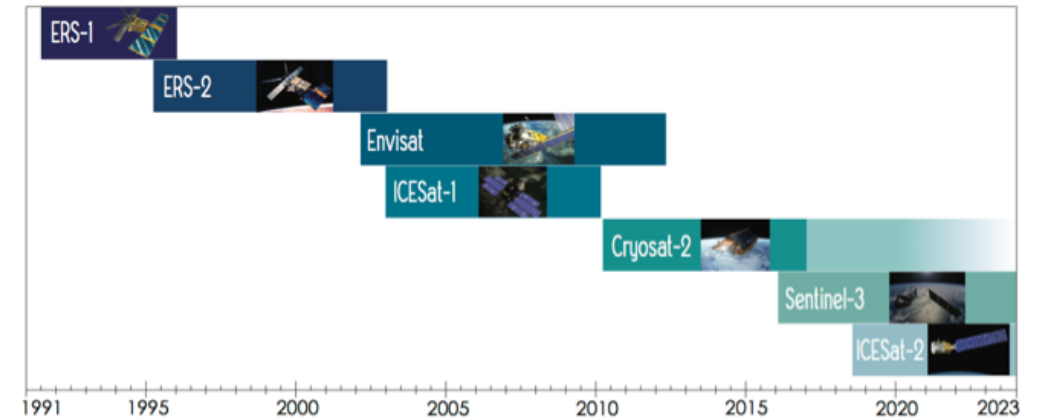
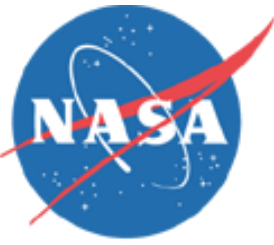
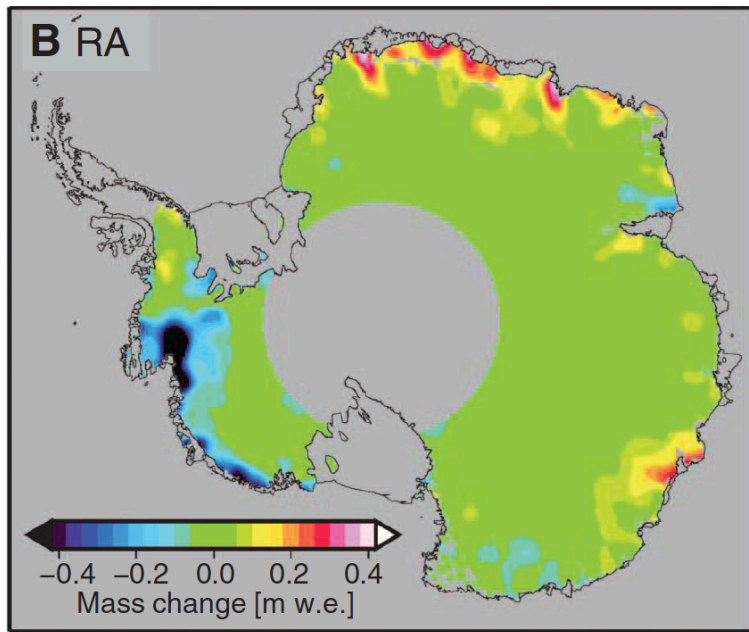


Figure 1. Past, present and future altimetry record

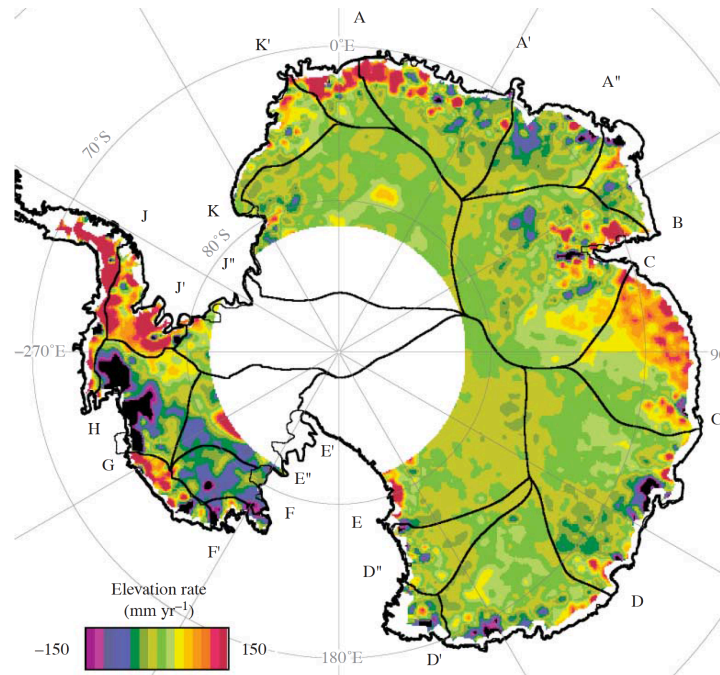
Elevation Change of the Antarctic Ice Sheet



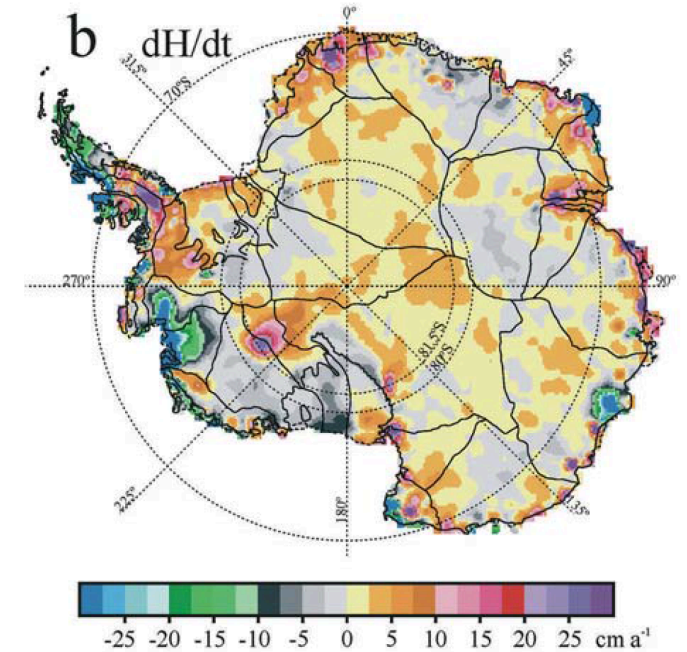
Multi-mission elevation change rates:



Shepherd et al. 2012



Wingham et al. 2006



Zwally et al. 2005



Methodology and Data

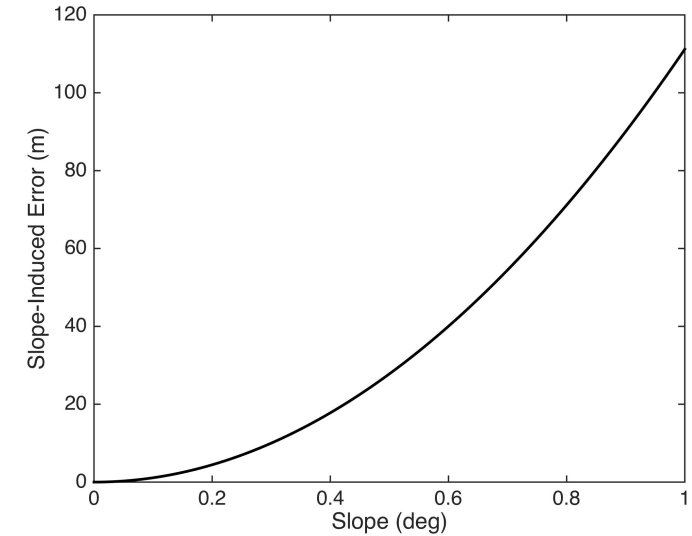
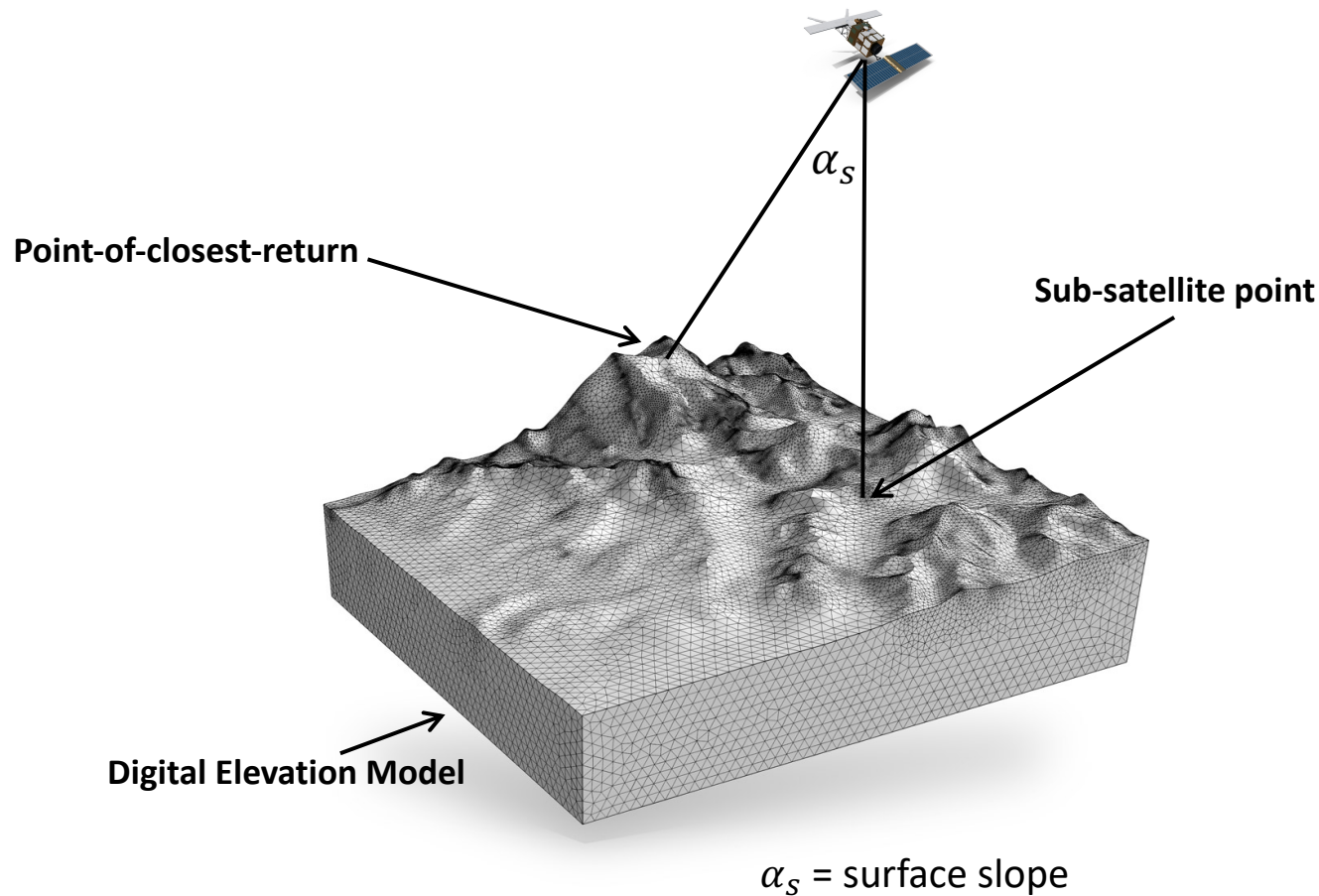
Processing Methodology:

- Slope Correction
- Topography Removal
- Scattering Correction
- Time Series Adjustment
- Sensor Fusion

Satellite Altimetry Records:

- ERS-1 REAPER
- ERS-2 REAPER
- Envisat L2 (GDR)
- ICESat NSIDC R34
- CryoSat-2

Slope Correction



- Largest error source for radar altimeters!
- Quality of correction depends on DEM accuracy
- Laser and "SARIn" largely insensitive to surface slope!



Topography Removal

- Removal of time-invariant surface to acquire temporal changes in elevation
 - 2-D: Along and Cross-track direction
- Least-squares fitting of mathematical surface model:
 - Biquadratic (1)
 - Bilinear (2)
 - Mean (3)
- Time Series: $dH(t) = H(t) - H(t)_m + E$

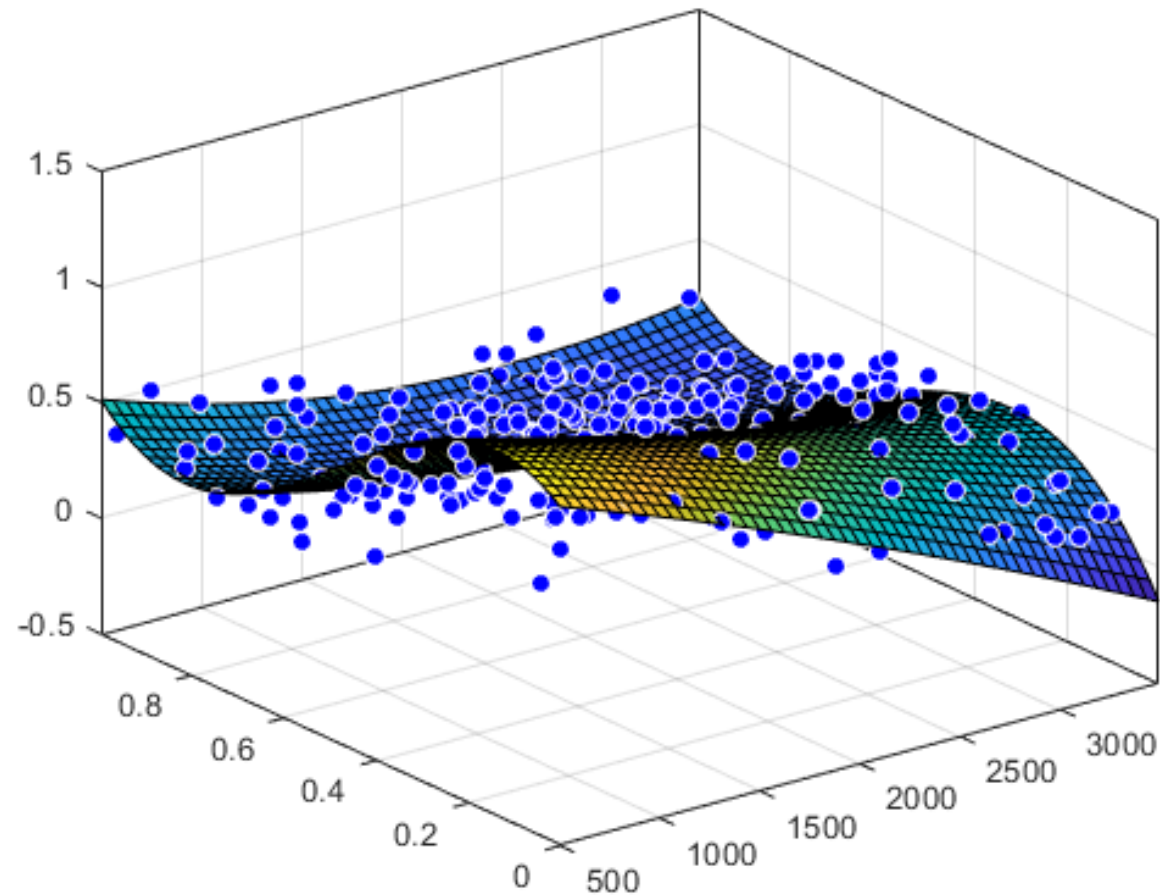
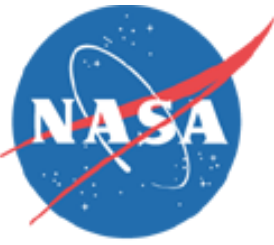


Image credit: Mathworks

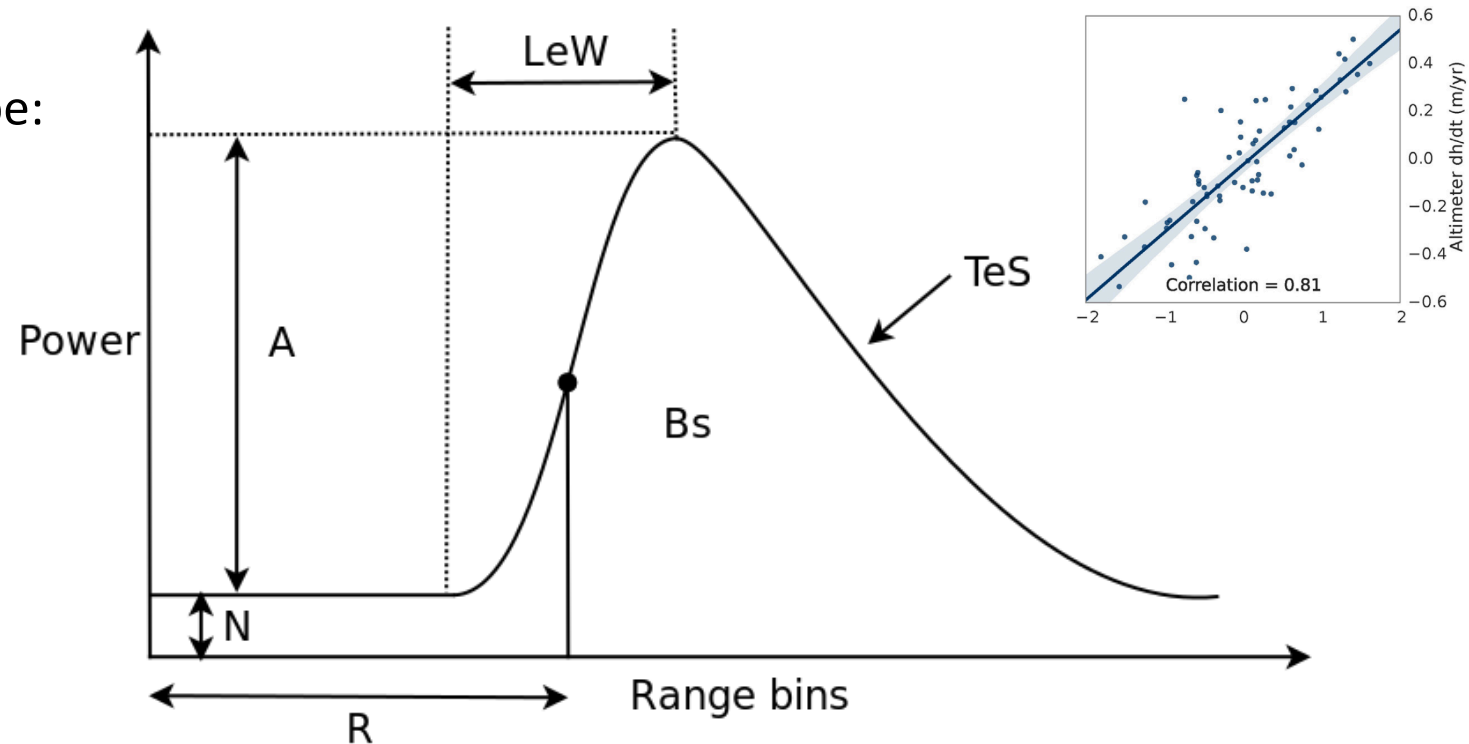


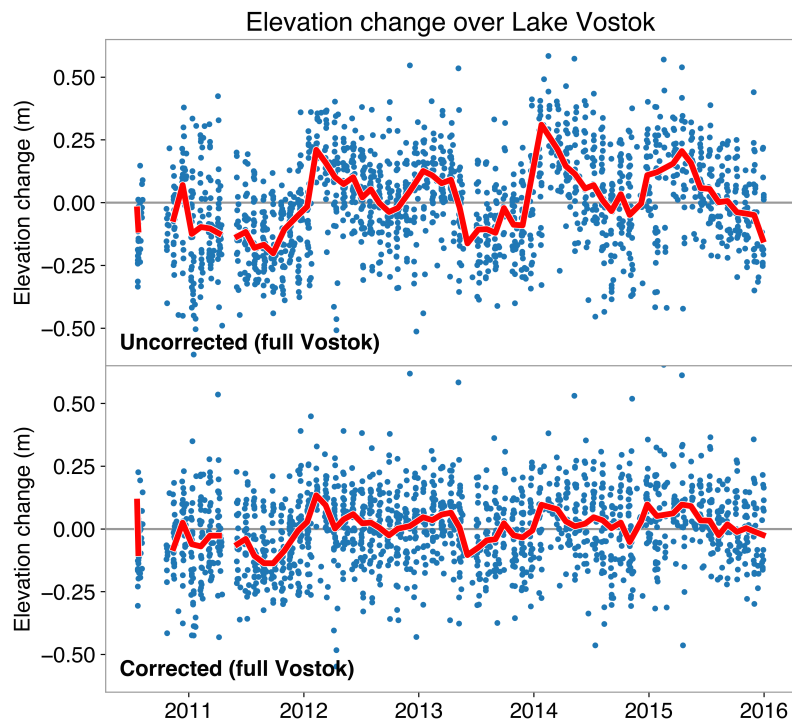
Scattering Correction – Radar (Ku-band)

Minimizing correlation between surface elevation and changes in waveform shape:

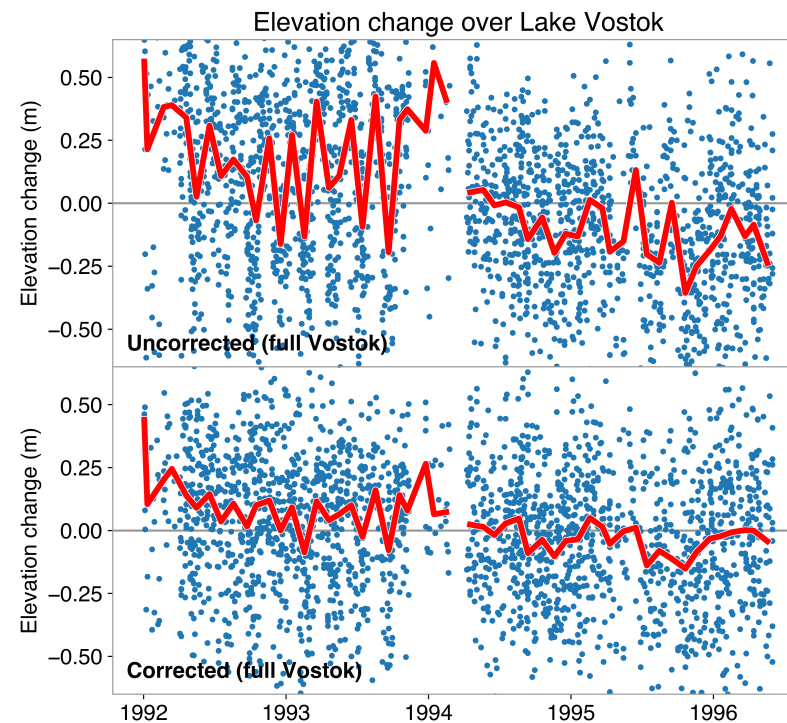
- Backscatter (**Bs**)
 - Surface regime or type
- Leading Edge Width (**LeW**)
 - Penetration
- Trailing Edge Slope (**TeS**)
 - Surface/Volume ratio

The magnitude of the correction depends on the sensitivity gradients between **dH** and **f(Bs, LeW, TeS)**

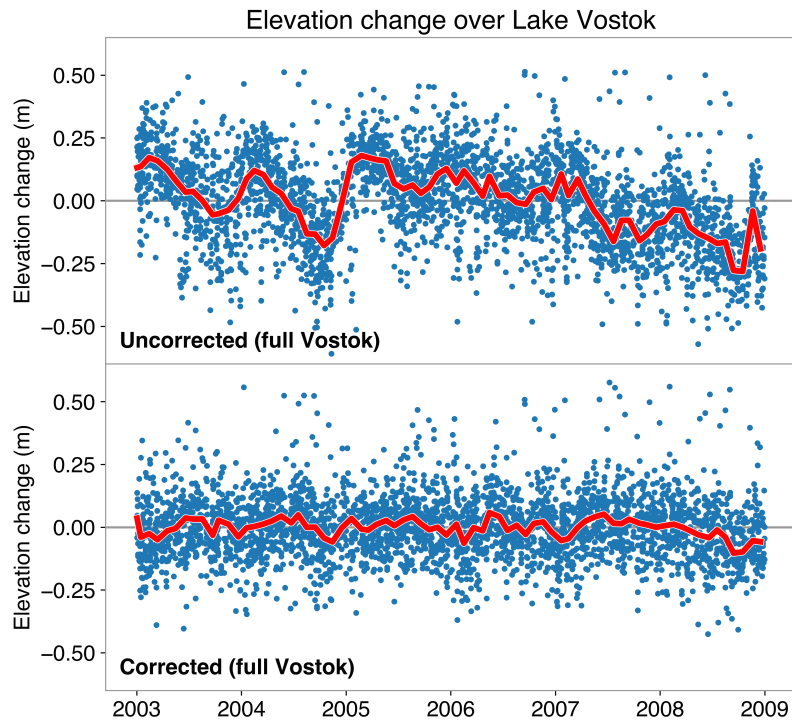
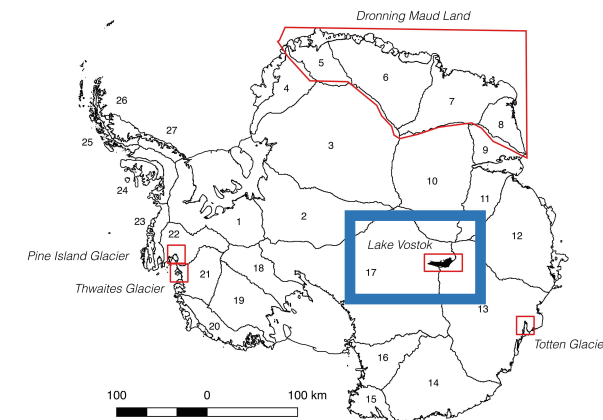




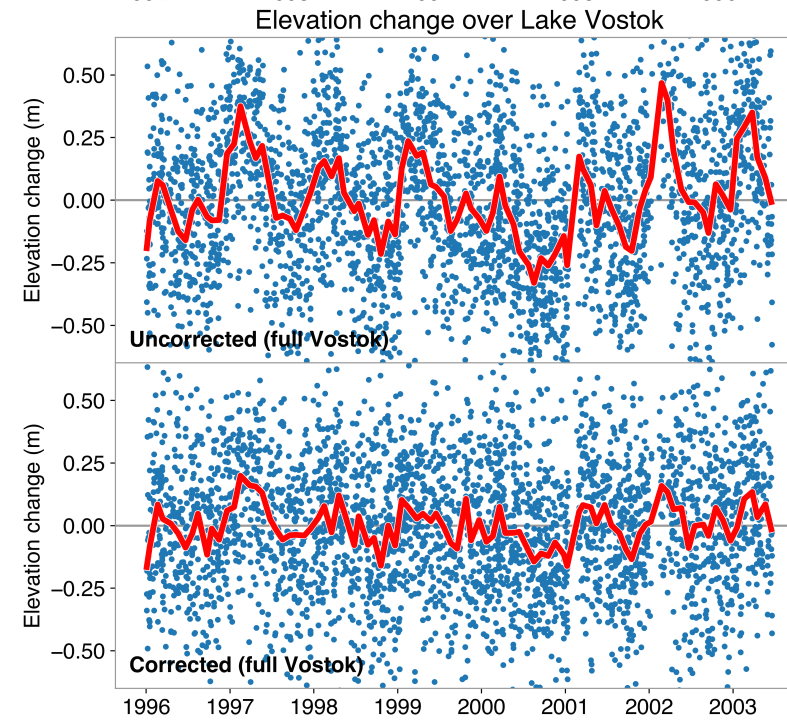
CS-2



ERS-1



RA-2



ERS-2



Time Series Adjustment

A least-squares adjustment is applied to align each sensor and to create continuous time-series:

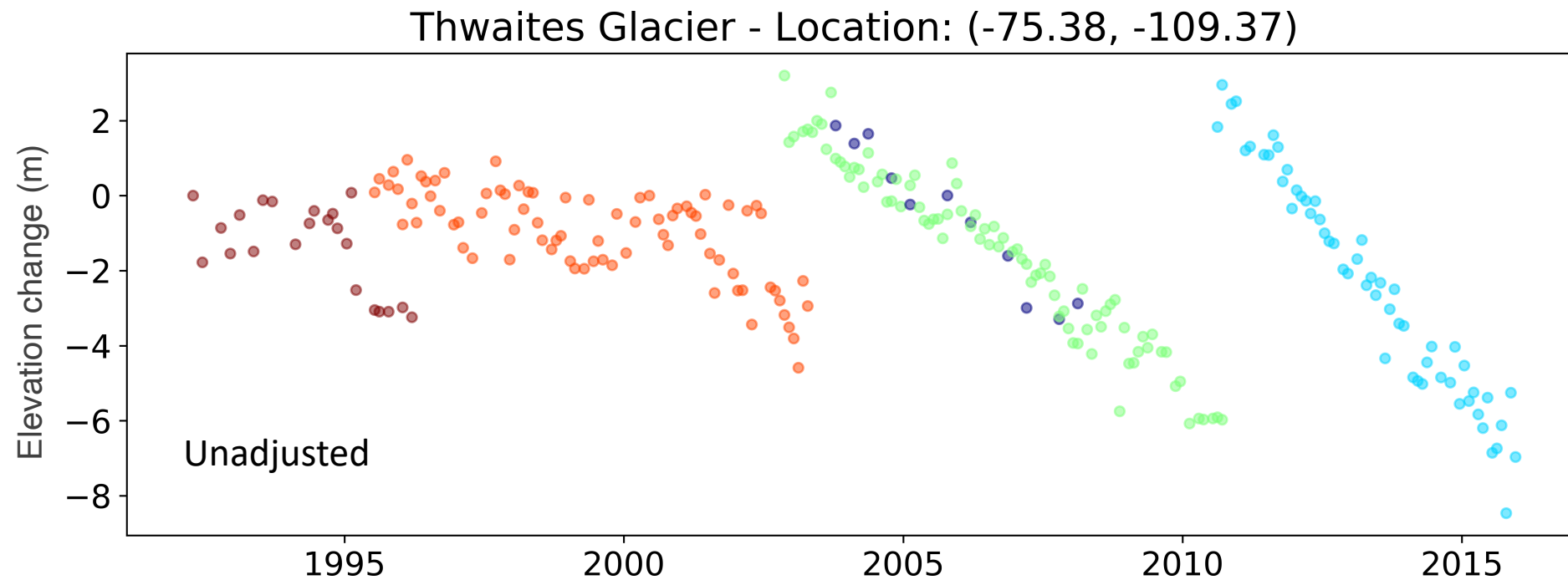
Divided into three sub-models:

$$\mathbf{x}(t) = \mathbf{x}_{trend} + \mathbf{x}_{step} + \mathbf{x}_{cycle}$$

comprising of trend (trend), mission offsets (step) and seasonality (cycle).

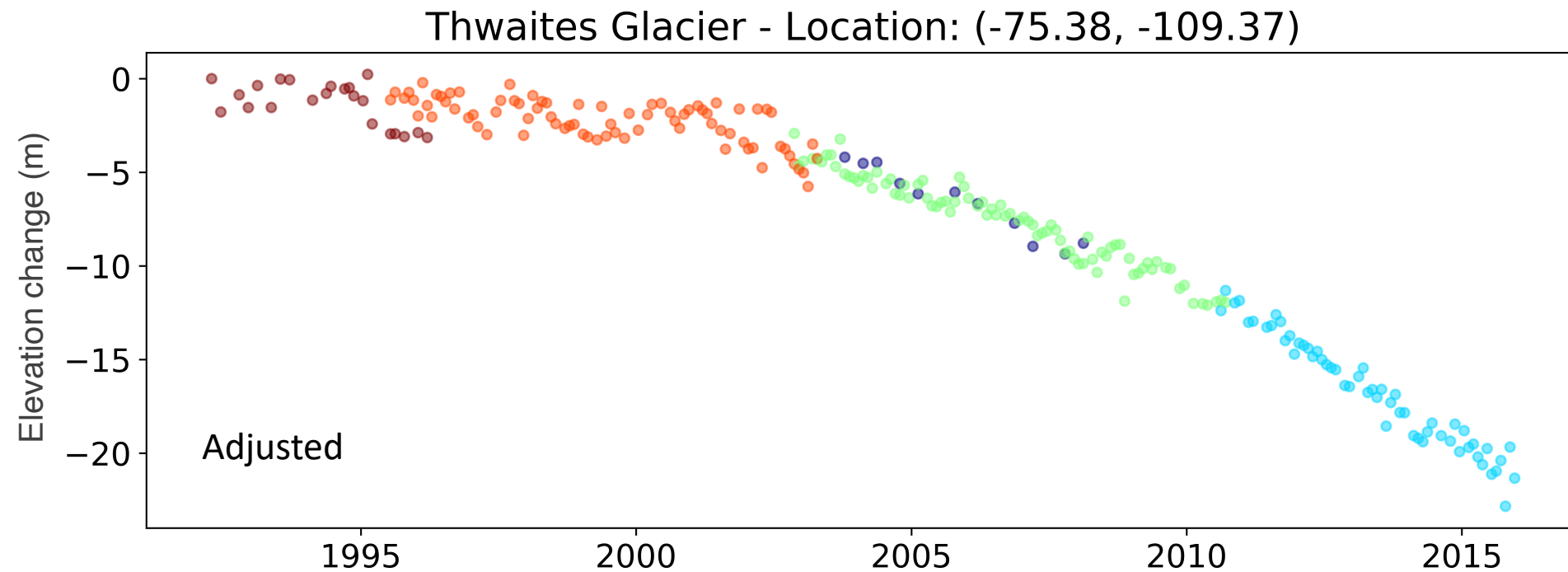


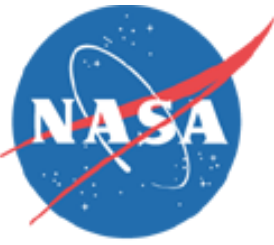
Time Series Adjustment – Single Pixel



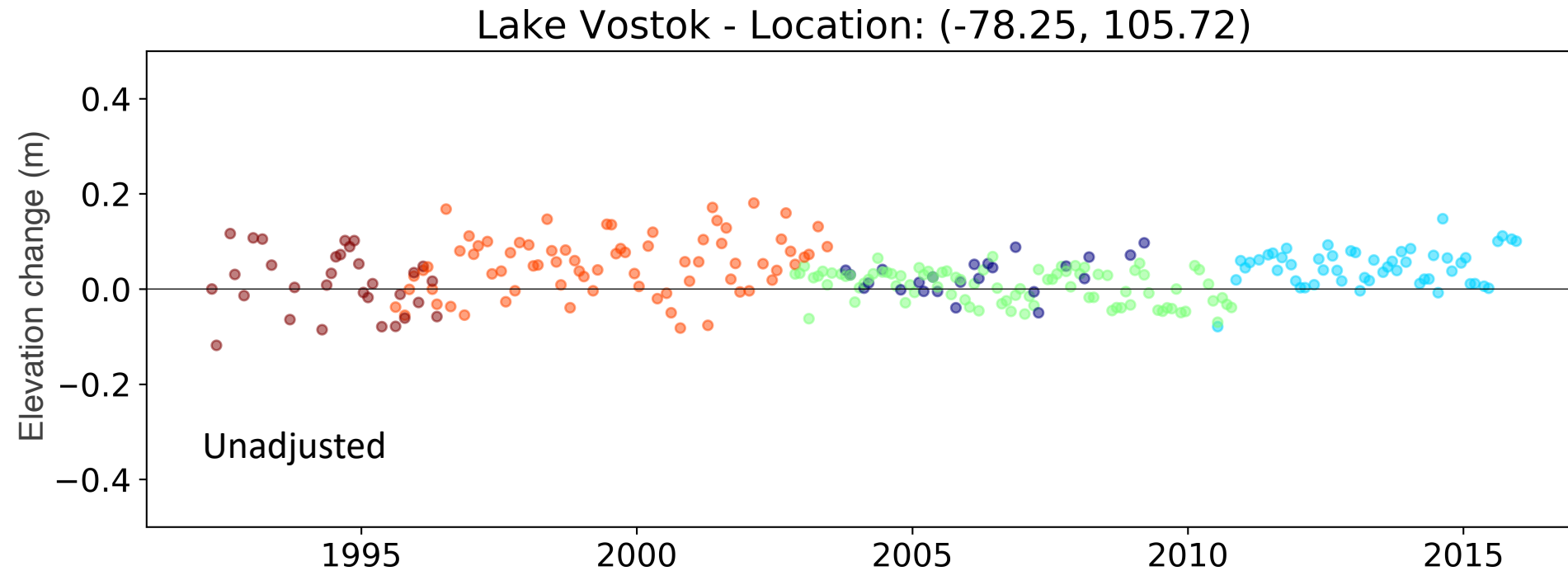


Time Series Adjustment – Single Pixel



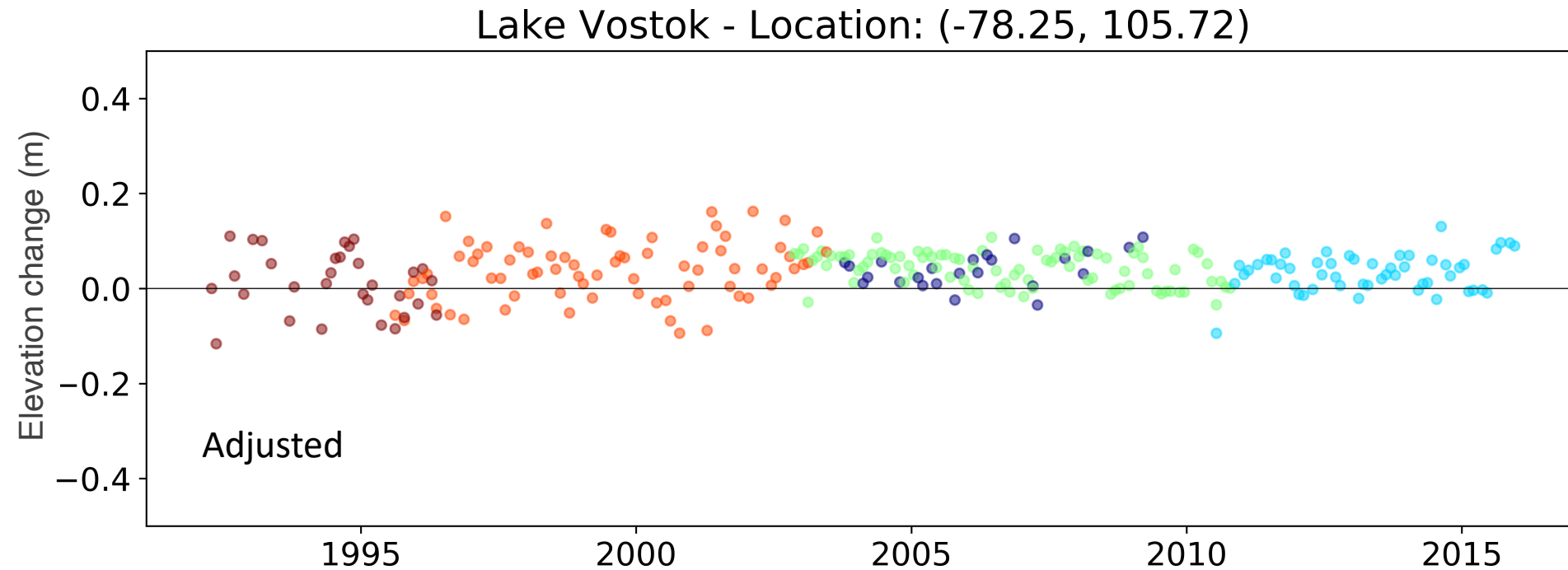


Time Series Adjustment – Single Pixel





Time Series Adjustment – Single Pixel





Sensor Fusion - Kalman Smoother

- Kalman Filter Equations:

$$\mathbf{x}_{k+1} = \mathbf{F}_k \mathbf{x}_k + \mathbf{w}_k$$

$$\mathbf{z}_{k+1} = \mathbf{H}_k \mathbf{x}_k + \mathbf{v}_k$$

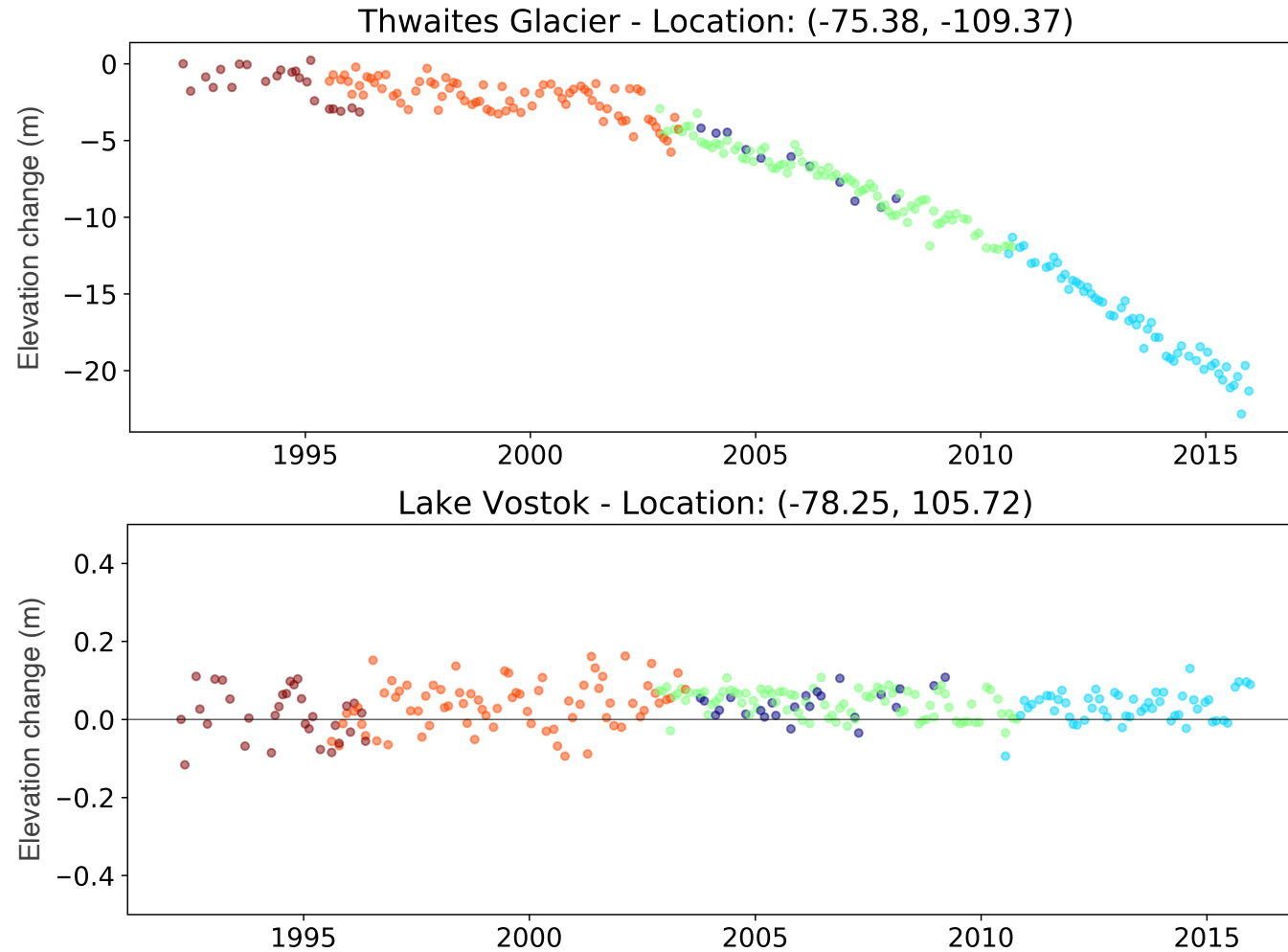
- State-Space Model:

$$y(t) = y_0 + v(t)t + s(t) \sin(\omega t) + c(t) \cos(\omega t)$$

- Model as Random-Walk “(t)”

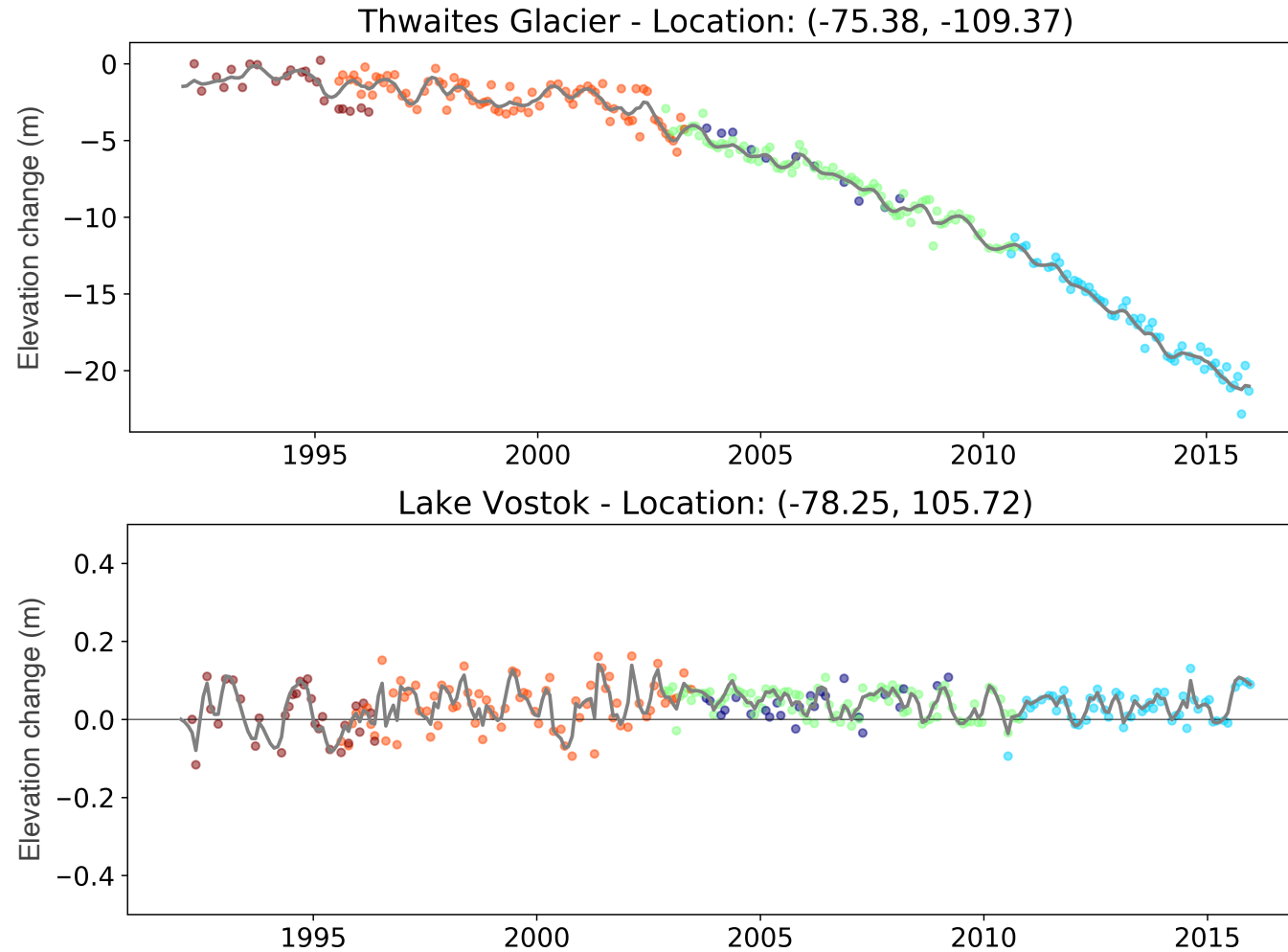


Sensor Fusion – Single Pixel

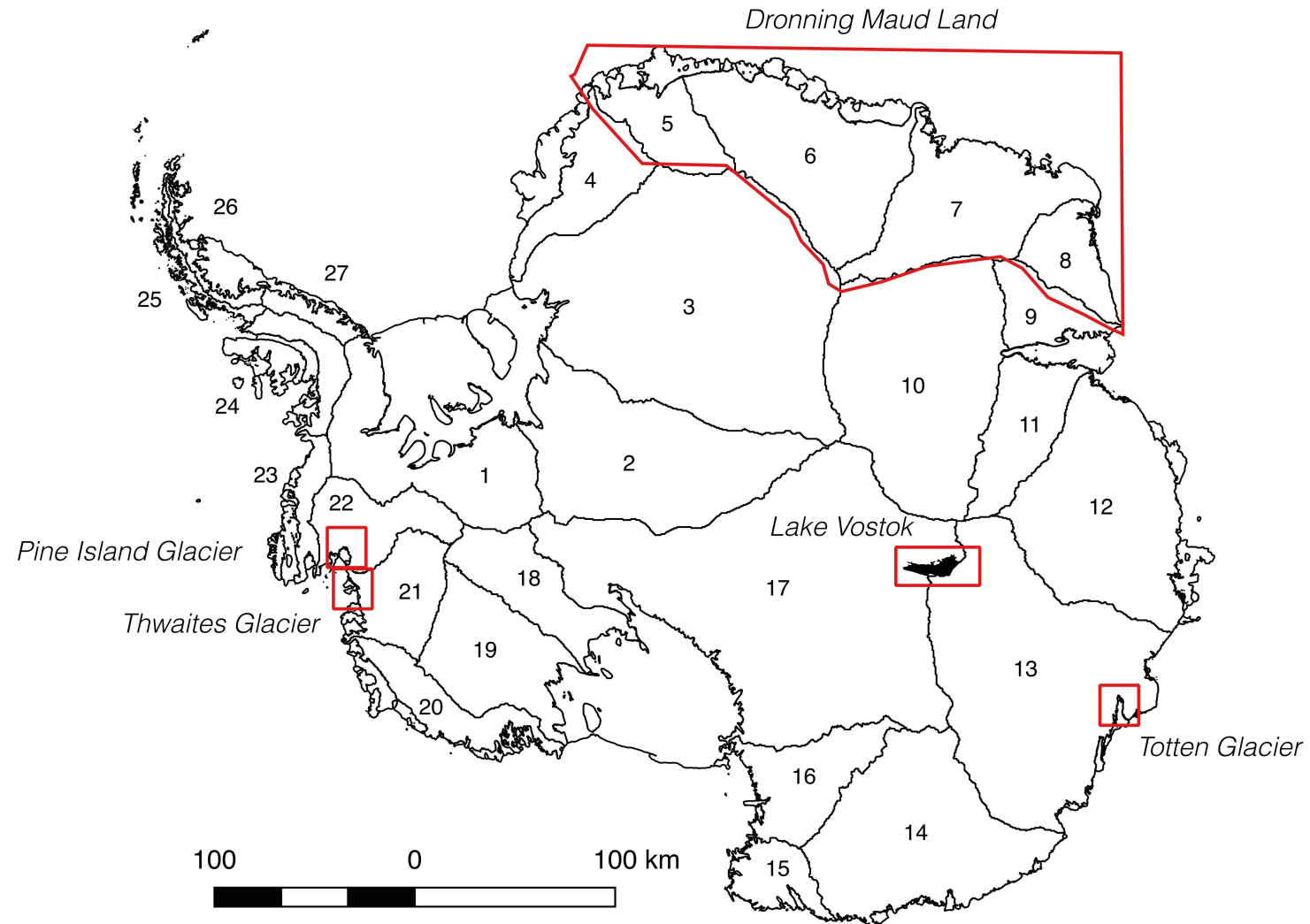




Sensor Fusion – Single Pixel

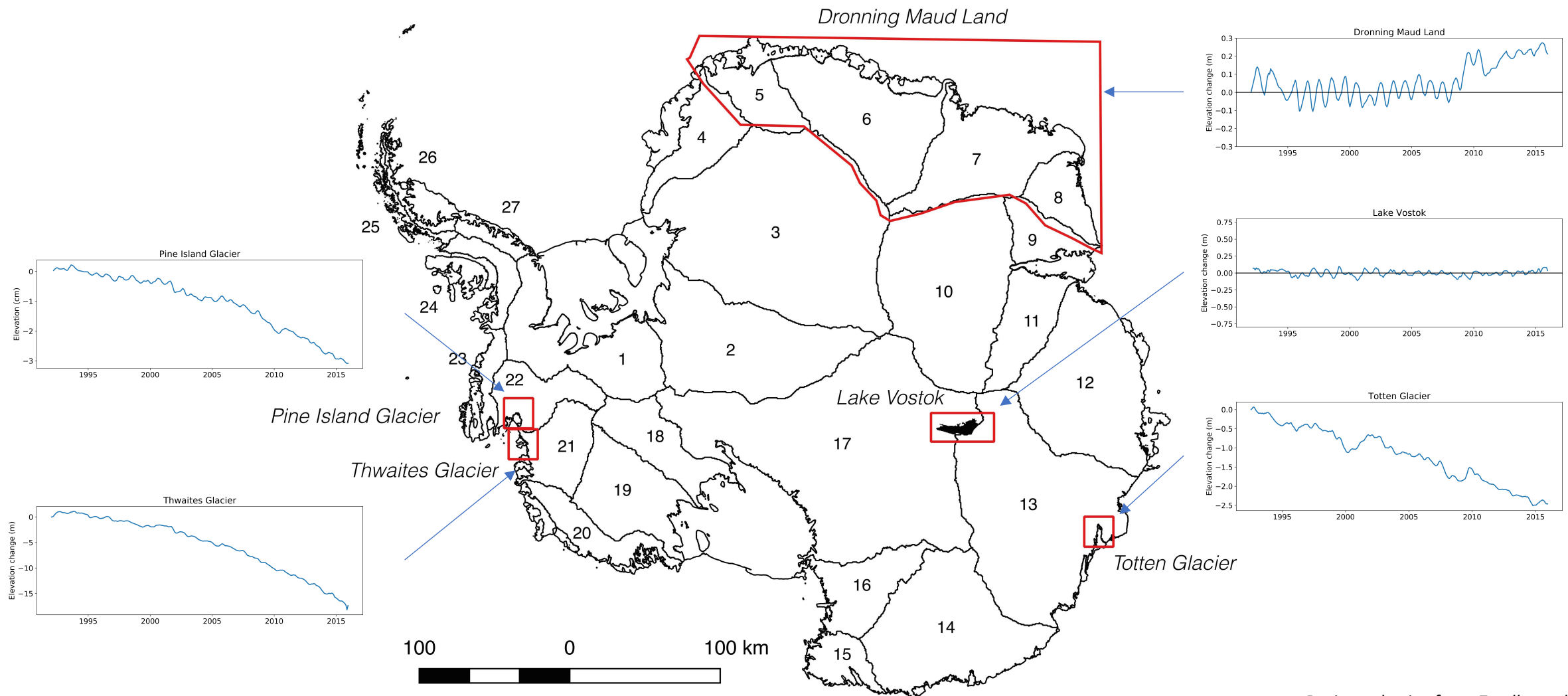


Regions of Interest



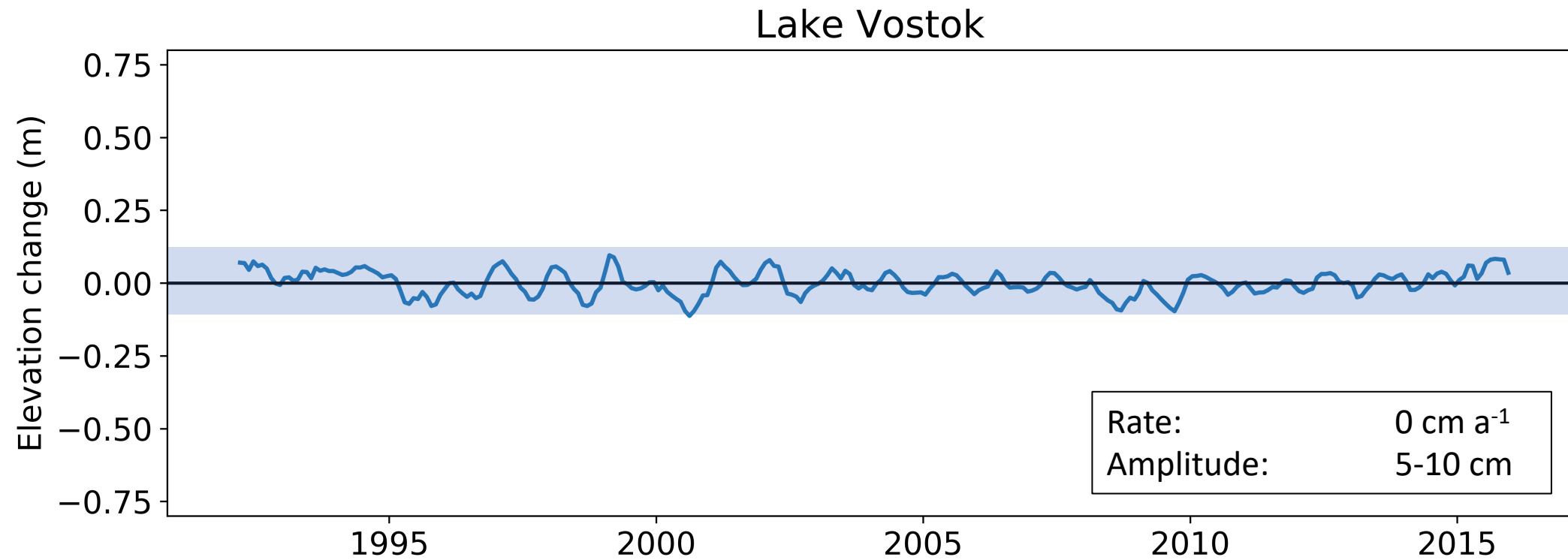


Regions of Interest



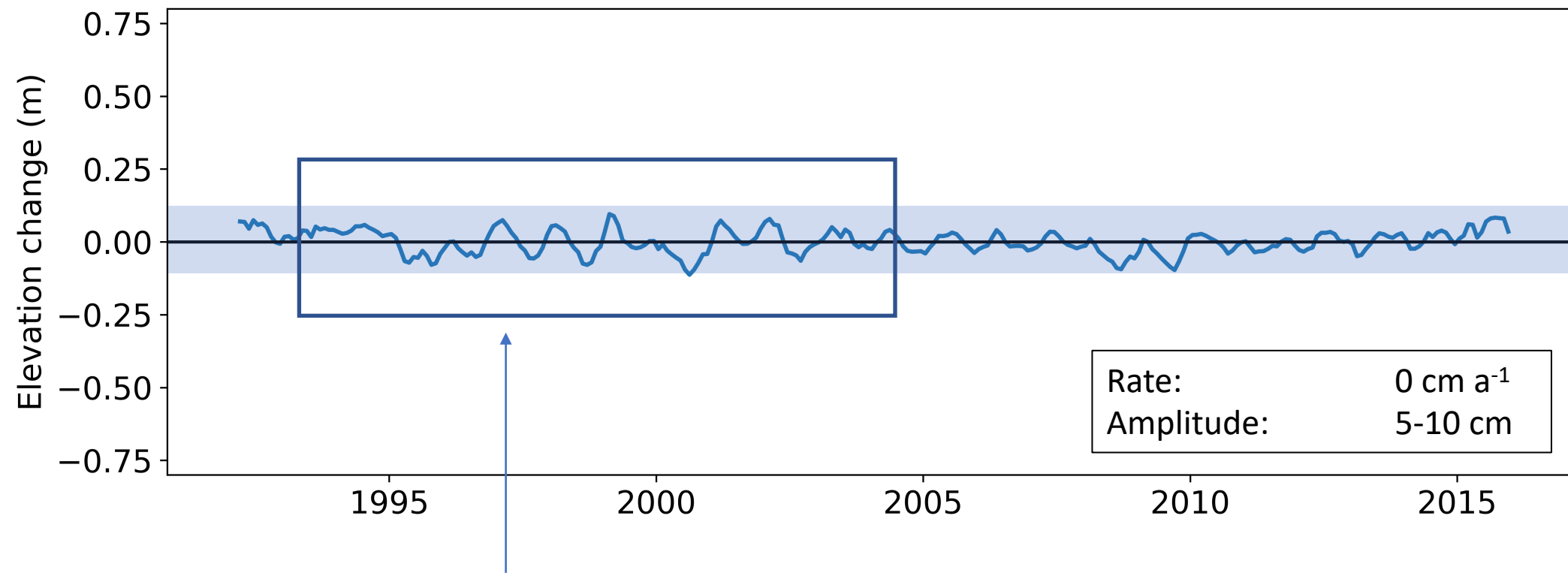


Lake Vostok





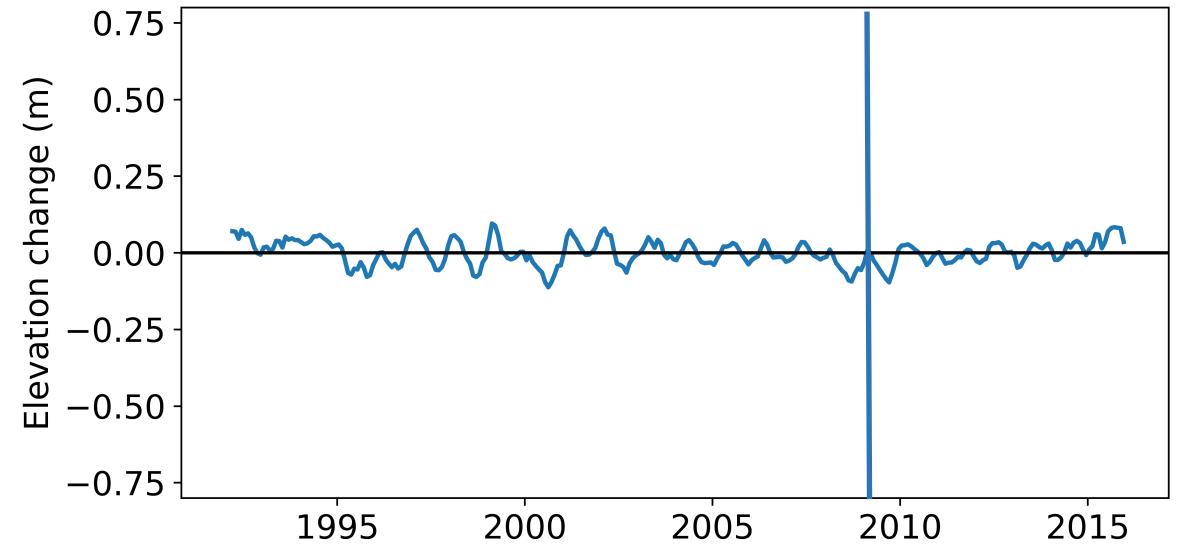
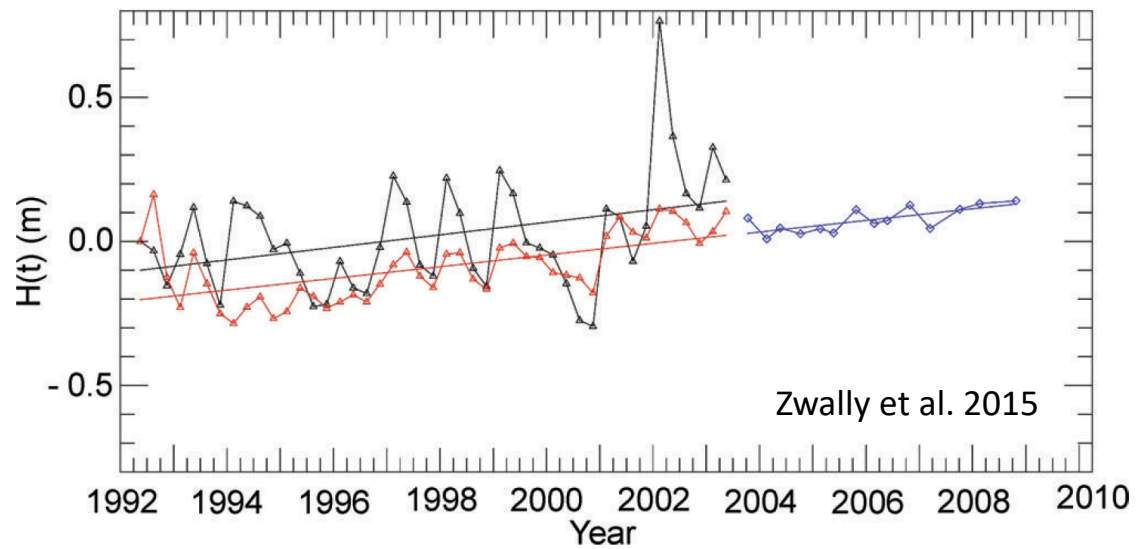
Lake Vostok

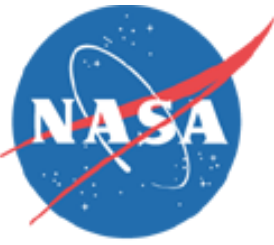


Larger seasonal amplitude due to noise in the older ERS-1/2 data!

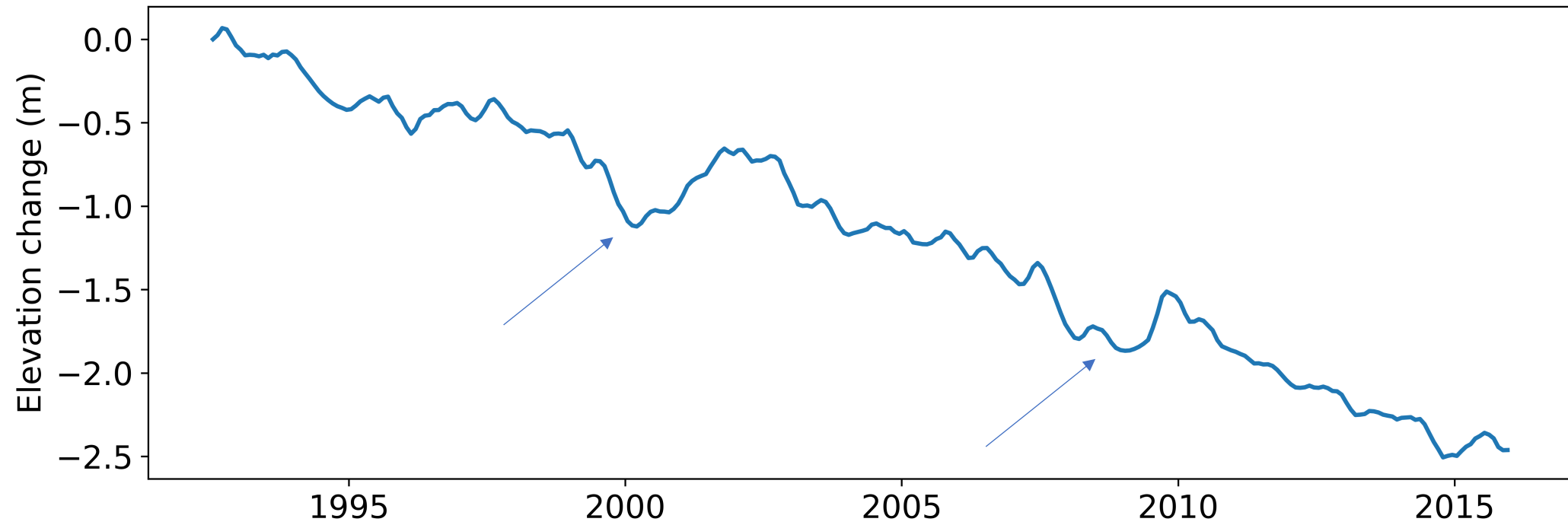


Lake Vostok – Comparison



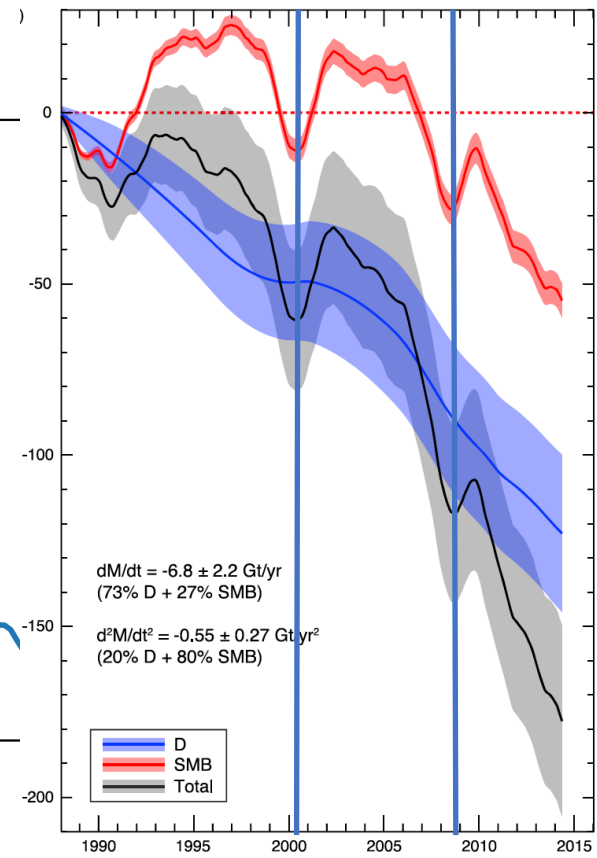
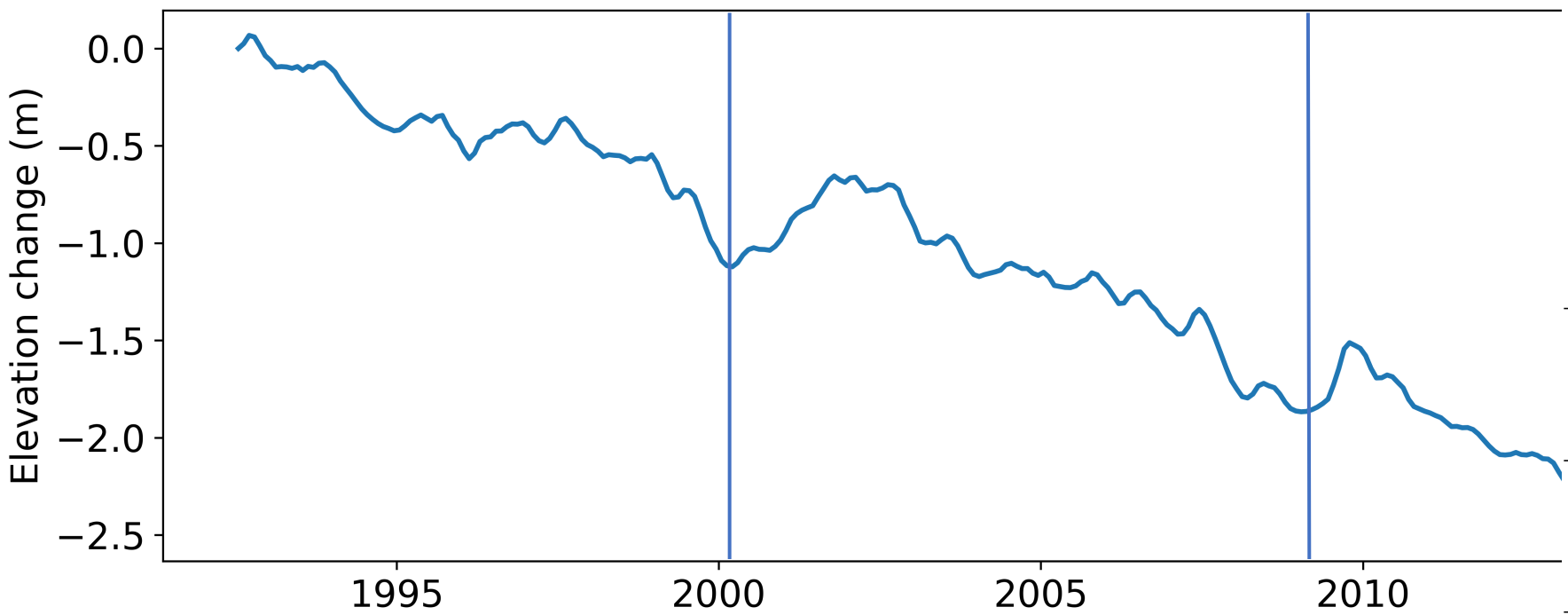


Totten Glacier





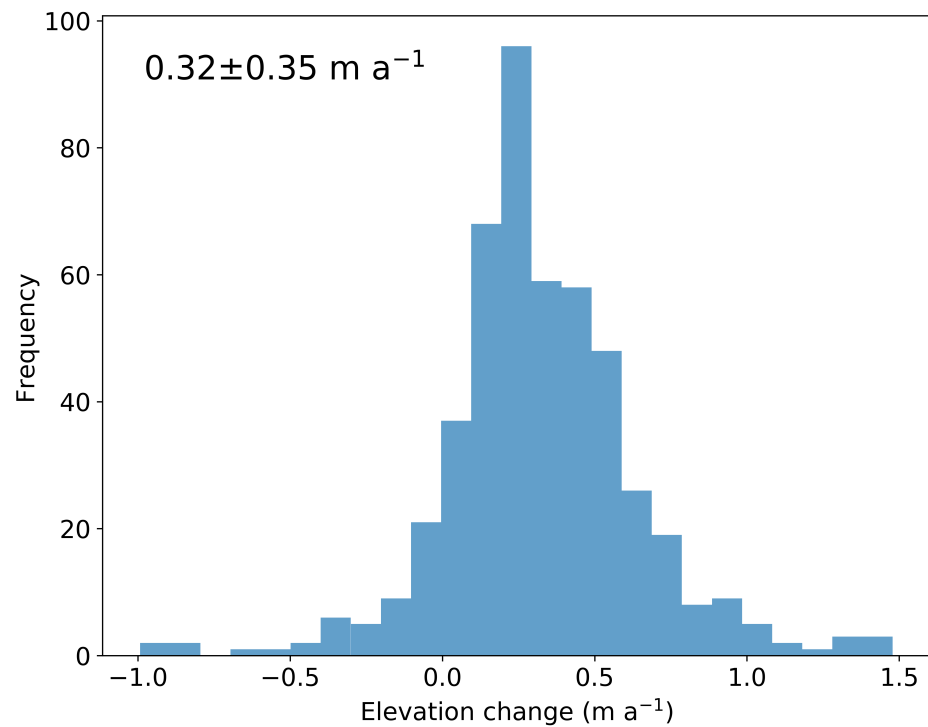
Totten Glacier



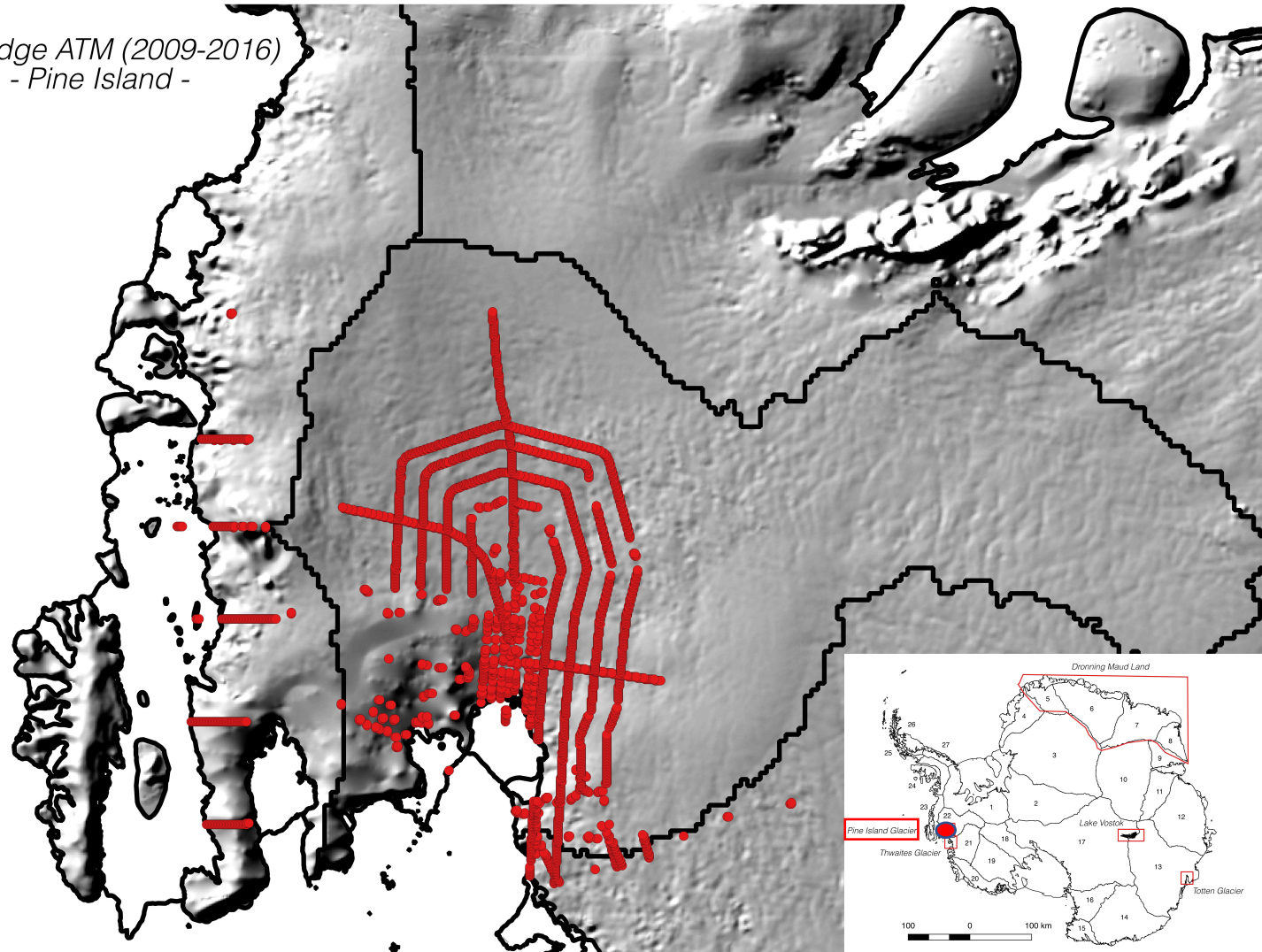
Li et al. 2016



Validation to Operation IceBridge

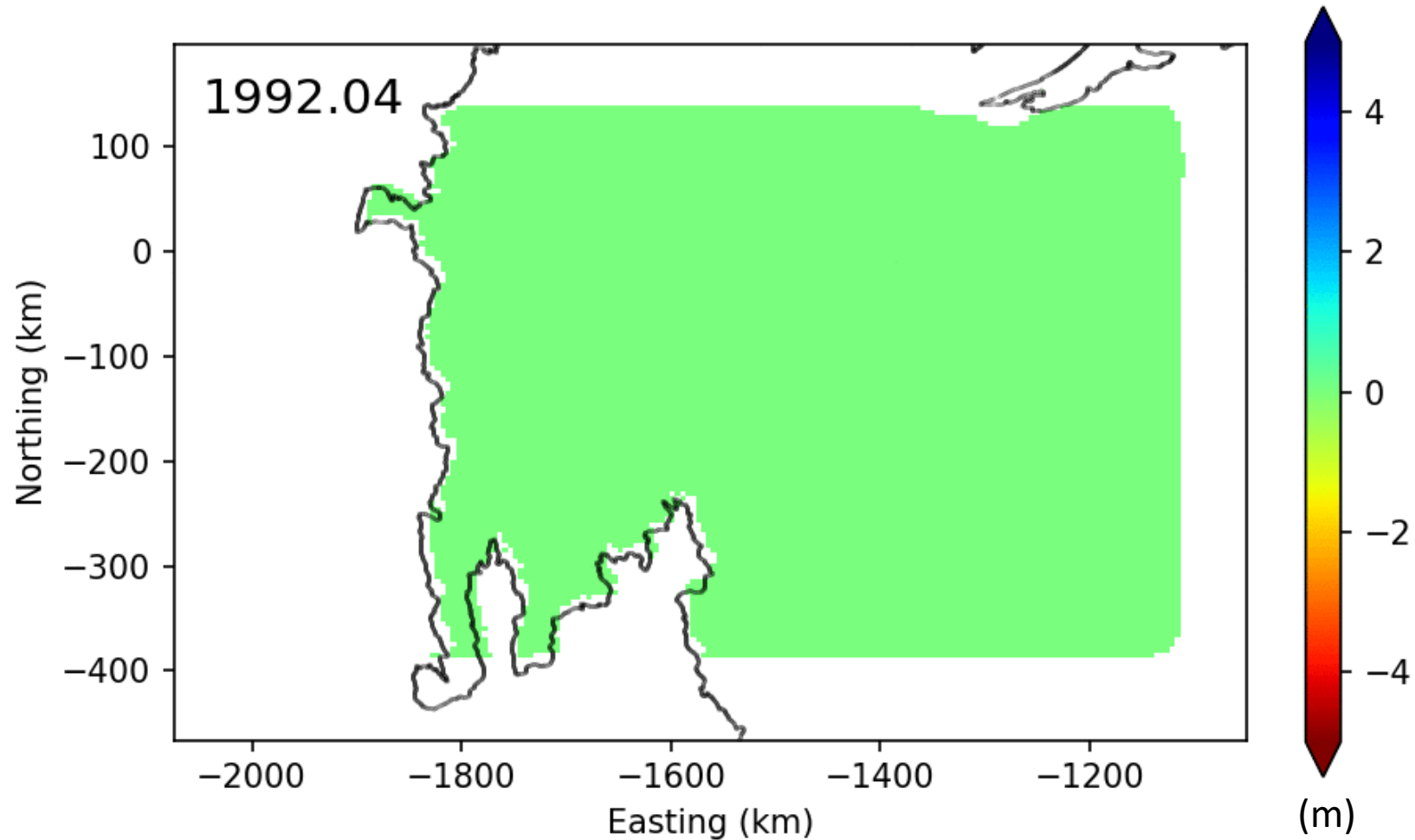


*IceBridge ATM (2009-2016)
- Pine Island -*





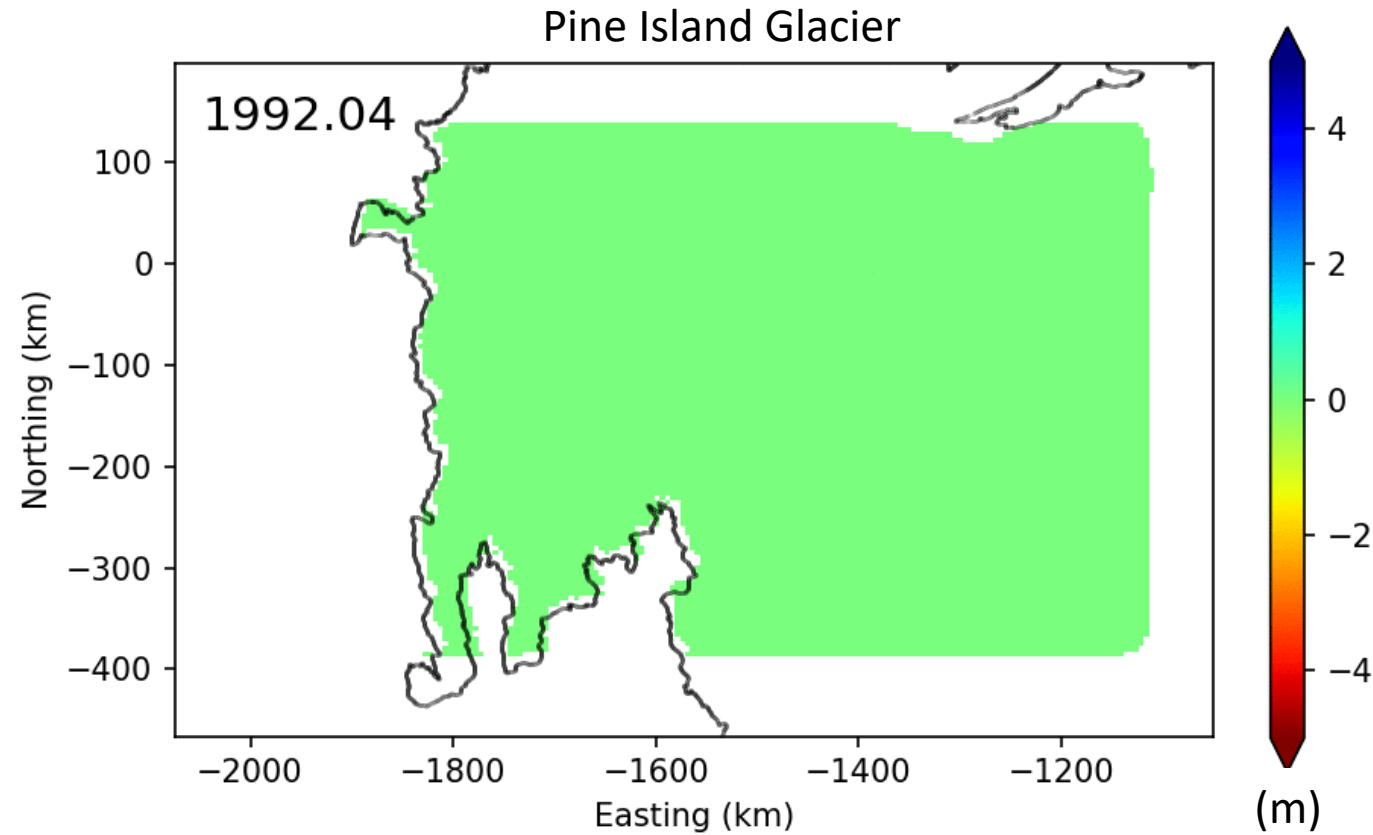
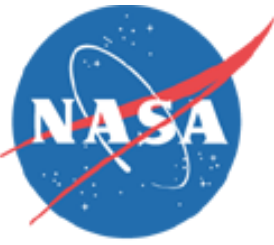
Pine Island - Temporal Evolution





Summary and Conclusions

- Procedure allows for reconstructing time series at fine spatio-temporal scales, while accounting for sensor-dependent biases and heterogeneous data quality.
- Analysis show that our applied correction minimizes the effects of surface slope, scattering regime and mission offsets.
- Initial validations show good agreement with ATM derived rates for the time period 2009-2016.
- Older missions show large noise variability (2x), which impacts the physical interpretation of the seasonal signal and possibly trend.
- Corrections applied to the altimetry observations are **non-trivial**: They affect trend, seasonality and the merging procedure
- Hence, extensive analysis is required to advance the current state-of the art methods for deriving reliable elevation trends and seasonal signals.



Thank you for listening!

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